

IIS

# GNSS RECEIVER WITH OPEN SOFTWARE INTERFACE (GOOSE)



Embedded version of GNSS receiver platform

The GOOSE platform is an FPGA based GNSS receiver. It is therefore flexible in processing new or proprietary signals. It comprises 60 hardware channels in real time and provides an open software interface for customer applications. It grants deep access to the hardware interface, down to e.g. integrate and dump value levels. Additionally, the intermediate frequency signals can be recorded, processed and replayed with the platform. GOOSE is meant as a rapid prototyping solution for the development of state of the art GNSS receivers. The platform is dedicated to software developers and mobile communication operators. It is also characterized by four separate components: a multi-frequency GNSS antenna, an analog-frontend board, a baseband board, and the processor system.



Record and replay version of GOOSE

## Main benefits

- Flexible development platform with multi-system and multisignal real-time processing
- Digital recording of intermediate frequency (IF) signals for SDR algorithm evaluation (post-processing)
- Analytic preprocessing of recorded IF-signals for replay
  - Insertion of Jamming and Spoofing
  - Mitigation of Jamming by Notch-Filter or Pulse-Blanker
- Digital Replay of IF-signals for easy and real-time repeatable tests
- Integrated antenna receiver combination (smart antenna)
- Guaranteed stable phase center for all GNSS frequencies
- Deployment in commercial PC or as an embedded platform
- Deep coupling and vector tracking in real time
- Extendable for meta signals
- Access to correlation values

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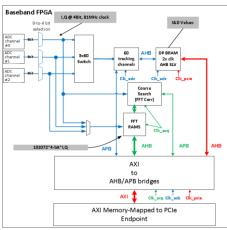
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### **Features**

- 60 hardware channels
- Up to 25 Hz Raw data output (code, carrier, navigation data)
- Supported signals:
  - GPS (L1 C/A, L2C, L5)
  - Galileo (E1BC, E5a/E5b, E5 (AltBOC))
  - Optional SBAS (EGNOS)
  - GLONASS (G1, G2)
  - BeiDou (B1, B2) ready
- Open GNSS Receiver Protocol (OGRP), fully documented with parsing tool using CONVBIN from RTKLIB as RINEX converter
- C++-API to access the tracking I&D values and to close the tracking loops
- Logging of tracking I&D values



Baseband implementation scheme

- 10 MHz reference input
- 10 MHz reference output
- x PPS output (1 Hz max. 25 Hz)
- 1 Ethernet port
- 2 full speed USB ports
- Digital recording and playback of front-end IF samples in real time

# **Performance**

1 PPS out jitter: 12 ns1 PPS out rise time: ~ 3 ns

Cold start: 32 s, without startup time of SBCWarm start: 20 s, without startup time of SBC

Re-acquisition: 1 - 2 s until satellite is again used in position solution

Tracking: down to 30 dBHzAcquisition: from 35 dBHz

# **Technical Details**

Dimensions housing (HxD): 20 x 17 cm

Dimensions electronic cube including antenna (HxWxD):
7 x 10 x 10 cm

• Weight electronic cube (incl. antenna): 350 g

Weight electronic cube only: 220 g

• Weight dome housing: 350 g

Weight PRoPART housing: 1.1 kg

Power: Input voltage: 6 - 36 V

Power consumption: ~ 13 W

 Antenna LNA power output: output voltage 3.3 V, maximum current 100 mA

Connectors:

Antenna: SMAREF IN: SMA

REF OUT: SMA

PPS OUT: Pin header

Power: 3.5"

COM1: Pin headerCOM2: Pin header2x USB 2.0 Type A

Ethernet RJ45

The GOOSE platform has been developed within the framework of the GOOSE project (German acronym for »GNSS Receiver with open software interface«) by Fraunhofer Institute for Integrated Circuits IIS from 2014 to 2015 and has been extended for rail application in the Galileo-Online: GO! project from 2015 to 2018. Both supported by the German Federal Ministry for Economic Affairs and Energy. Presently, the GOOSE platform is used for autonomous truck driving in the PROPART project supported by GSA.